

# Second Moment Estimation

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For a given  $n \times m$  generator matrix  $\mathbf{B}$  with linearly independent rows, a lattice  $\mathcal{L}$  consists of the points  $\mathbf{u}\mathbf{B}$  for all  $\mathbf{u} \in \mathbb{Z}^n$ . By definition, the all-zero vector  $\mathbf{0}$  belongs to any lattice. The inner products of all basis vectors with each other are collected in the symmetric, positive definite Gram matrix  $\mathbf{A} = \mathbf{B}\mathbf{B}^T$ . The set of vectors in this subspace that are closer to  $\mathbf{0}$  than to any other point in  $\mathcal{L}$  is the Voronoi region  $\Omega$  of the lattice. The normalized second moment (NSM) [1], [2, pp. 34, 56–62] is

$$G = \frac{1}{nV^{1+2/n}} \int_{\Omega} \|\mathbf{x}\|^2 d\mathbf{x}, \quad (1)$$

where  $V = (\det \mathbf{A})^{1/2}$  is the  $n$ -volume of  $\Omega$ .

An elegant method to generate random vectors uniformly in the Voronoi region  $\Omega$  of a given lattice was proposed in [3] for the purpose of NSM estimation. Let  $\mathbf{z}$  be a random vector drawn uniformly from the unit  $n$ -cube  $[0, 1]^n$  and let, for a given generator matrix  $\mathbf{B}$ ,

$$\hat{\mathbf{u}} = \arg \min_{\mathbf{u} \in \mathbb{Z}^n} \|(\mathbf{z} - \mathbf{u})\mathbf{B}\|^2. \quad (2)$$

Now  $\hat{\mathbf{u}}\mathbf{B}$  is the lattice point closest to  $\mathbf{z}\mathbf{B}$  (which is normally not a lattice point). Therefore,  $\mathbf{e} = (\mathbf{z} - \hat{\mathbf{u}})\mathbf{B}$  is uniformly distributed in  $\Omega$ . To calculate (2) requires solving the *closest point problem* for a given lattice. Algorithms for this purpose are available for classical, well-structured lattices [3], [4] as well as arbitrary lattices [5], [6].

Using these definitions of  $\mathbf{z}$ ,  $\hat{\mathbf{u}}$ , and  $\mathbf{e}$ , the NSM in (1) can be written as

$$G = \mathbb{E}_{\mathbf{z}}[g(\mathbf{B}, \mathbf{z})], \quad (3)$$

where

$$g(\mathbf{B}, \mathbf{z}) = \frac{1}{n} V^{-2/n} \|\mathbf{e}\|^2. \quad (4)$$

Here  $V$  is a function of  $\mathbf{B}$  and  $\mathbf{e}$  is a function of both  $\mathbf{B}$  and  $\mathbf{z}$ .

If  $\mathbf{z}_1, \dots, \mathbf{z}_T$  denote  $T$  independent realizations of  $\mathbf{z}$ , then an unbiased estimate of  $G$  follows immediately from (3) as

$$\hat{G} = \frac{1}{T} \sum_{t=1}^T g(\mathbf{B}, \mathbf{z}_t). \quad (5)$$

To quantify the estimation accuracy, the variance of  $\hat{G}$  can be estimated as [7, Sec. IV]

$$\hat{\sigma}^2 = \frac{1}{T-1} \left( \frac{1}{T} \sum_{t=1}^T g^2(\mathbf{B}, \mathbf{z}_t) - \hat{G}^2 \right), \quad (6)$$

which is much more accurate than the “jackknife” estimator recommended in earlier literature.

It is easily verified that (5) remains unchanged if the lattice, represented by  $\mathbf{B}$ , is rescaled. However, previous descriptions of the same NSM estimation method are valid only for lattices with  $V = 1$ . This is because of an unfortunate error in the original publication [3], where the right-hand sides of [3, Eqs. (2), (4)] are missing a factor corresponding to the volume of the Voronoi region (here denoted by  $V$ ). This error appears to have propagated to [8, Eqs. (73)–(74)] and [7, Eqs. (12)–(15)].

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